Ultrasonic sensor UB400-F42S-UK-V95

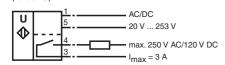


Features

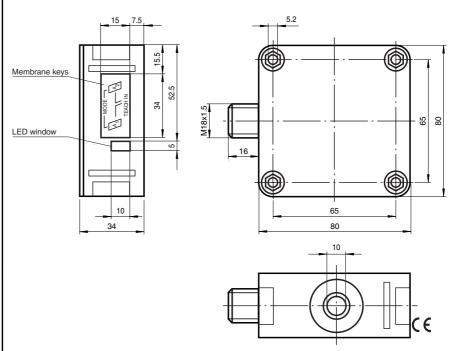
- · Relay output for high power
- Extremely small unusable area
- 4 operating modes can be set
- Temperature compensation
- NO/NC selectable

Electrical connection

Standard symbol/Connections: (version U)



Dimensions



Technical data

General specifications

Sensing range Adjustment range 30 ... 400 mm 50 ... 400 mm Unusable area Standard target plate Transducer frequency Response delay

Indicators/operating means

LED green LED yellow

LED red

Electrical specifications

Operating voltage No-load supply current I₀

Output

Output type Repeat accuracy Rated operational current I_e Switching frequency f Range hysteresis H Temperature influence Standard conformity

Standards Climatic conditions

Ambient temperature Storage temperature

Mechanical specifications Protection degree

Connection type Material Housing

Transducer Mass

. 30 mm 100 mm x 100 mm approx. 390 kHz approx. 50 ms

permanently green: Power on permanent: switching state switch output flashing: TEACH-IN function normal operation: "fault TEACH-IN function: no object detected

20 ... V DC ... 230 V AC

≤ 60 mA

1 relay output

≤ 0,5 % of switching point

3 A

≤ 8 Hz

1 % of the set operating distance

± 1 % of final value

EN 60947-5-2

-25 ... 70 °C (248 ... 343 K)

-40 ... 85 °C (233 ... 358 K)

IP65

connector V15 (M12 x 1), 5 pin

PBT

epoxy resin/hollow glass sphere mixture; foam polyurethane, cover PBT



Preliminary data sheet - only for information

TEACH-IN for switching points LED layout green (gn) cred (rd) | ○ | yellow (ye) Switching point 1 Target detected Target not detected Position the target object at the desired po-**1** > 2 s sition/distance. Press the A1 key > 2 s (rd) (time lock) (ye) Correct the object position or sensor alignment until object is detected. Acknowledge when The value of the object target is detected. distance will be stored. ● (ye) Switching point 2 Position the target ob-Target not detected > 2 s 👃 ject at the desired position/distance. Press the A2 key > 2 s or ● (rd) (time lock) (ye) 0 Correct the object position or sensor alignment until object is detected. The value of the object Acknowledge when target is detected. distance will be stored. ● (ye) If TEACH-IN mode is not acknowledged within 5 min., the sensor goes back into normal mode and retains the last values to be stored.

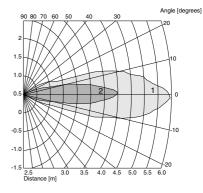
Switching between hysteresis mode - switching point mode or window mode			LED layout green (gn) red (rd) yellow (ye)
Hold down both keys at the same time. (time lock)	> 2 s	Current operating mode (gn) or Hysteresis mode New operating mode	(gn) Switching point mode
		(gn) or Switching point mode	(gn)
Release keys	A1 TEACH IN	5 s (gn)	5 s 💓 (gn)
If switching is not acknowledged within 5 min., the sensor goes back into normal mode and retains			

Model number

UB400-F42S-UK-V95

Characteristic curves/additional information

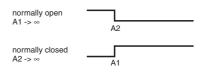
Characteristic response curves



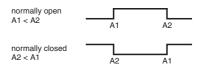
Curve 1: flat plate 100 mm x 100 mm Curve 2: round bar, Ø 25 mm

Possible operating modes

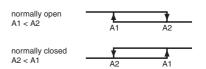
1. Switch point operation



2. Window operation



3. Hysteresis operation



4. Object presence detection mode

A1 -> ∞ , A2 -> ∞ : Sensor detects object presence within sensing range

Note A1 -> ∞ , A2 -> ∞ means: cover sensor with hand

Note A1 -> ∞, A2 -> ∞ means: cover sensor with ha or remove all objects from sensing range

Preliminary data sheet - only for information

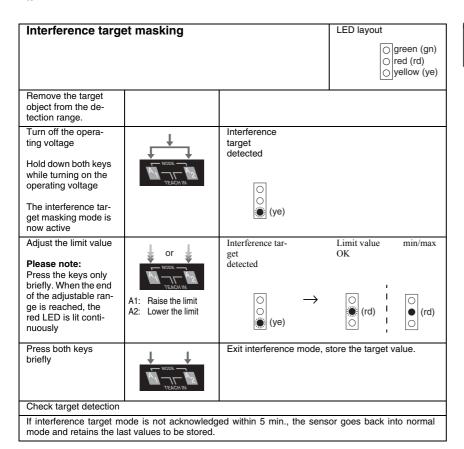
Interference target masking

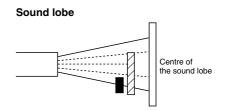
Interference target masking can be adjusted in 24 steps. Each brief keystroke on (A1) increase or (A2) decreases the limit value.

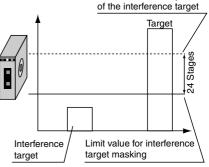
Permanently lighting red LED: max. or min. adjustment limit reached. Go back one step.

What is an interference target

- Small distance to the sensor as the actual target
- must not completely cover the actual goal
- The amplitude of the interference signal must be less than the amplitude of the usable signal.
- The interference target must be positioned only at the edge of the sound lobe and not in the center.







Limit value after adjustment